

Digital controller AN308



The AN308 module is a further development of the familiar AN307 controller. Whereas the AN307 is intended principally for the processing of analog signals, the development objective for the AN308 was the additional ability to process signals from digital displacement sensors. This allows the AN308 to be used as a CNC controller.

The sensor system is of universal design so that the widest variety of sensors can be evaluated by exchanging a module (e.g. 4...20mA, $\pm 10V$, $7.5V \pm 4V$). In addition, an integral medium-frequency generator permits the connection of an inductive displacement sensor.

Interfaces are provided for SSI transmitters, incremental transmitters and ultrasonic displacement sensors (MTS). The ultrasonic displacement sensor is evaluated directly in the module.

To permit direct control of a proportional valve, the module is provided with PWM output stages with high dynamic response, allowing peak currents of more than 3A with a carrier frequency of 6kHz. To permit better adaptation to different valves, the coil current has three plug-selectable ranges (800mA, 1600mA, 3000mA).

The use of a 32 bit computer system achieves short cycle times, allowing drives with high dynamic demands to be controlled.

The quadruple digital/analog converter (12 bit resolution) allows this unit to be used for a wide range of applications so that even an external servo or regulating valve can be controlled. The outputs can be switched between $\pm 10V$, $\pm 20mA$ and $\pm 10mA$.

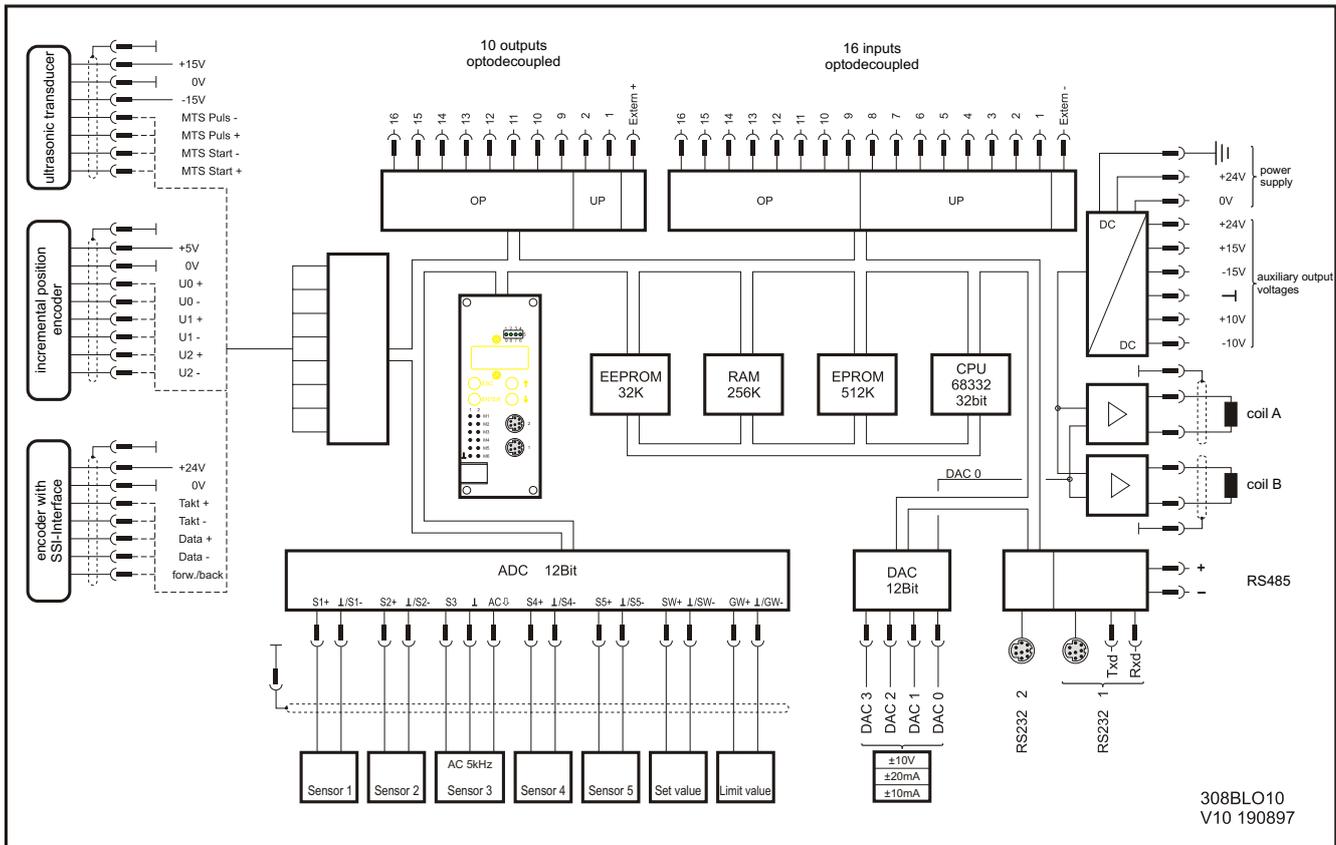
The circuit is designed to allow the speed and acceleration to be calculated from the displacement and pressure signals, so that these can be fed into the controller as status variables. A variety of adaptations to characteristics and of signal limitations, precontrols and inversions are possible. Up to 3 controllers can be operated in a cascade.

The controller module has 16 digital inputs and 10 digital outputs. The inputs are used to control the module (enable, setpoint selection, etc.), while the outputs, which are implemented as high side drivers, are intended as status displays. Inputs and outputs are optically insulated.

Parameter assignment and setpoint pre-setting takes place in sets via an external computer (PC) or via the optional keyboard in conjunction with a display.

Communication with the module is via the 16 inputs or optionally via the serial interface or the analog inputs.

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Technical Data:

Supply voltage	24V DC (18...32V DC)	CPU	Motorola MC68332
Auxiliary voltages	approx. +24V, not stabilised approx. +15V, not stabilised approx. -15V, not stabilised +10V, stabilised -10V, stabilised	Memory	RAM 256KB EPROM 128KB / 512KB EEPROM 32KB
Output stages	PWM output stage with high dynamic response PWM frequency approx. 6kHz	Data input	Parameters and setpoints entered via the serial interface or via the optional keypad and the 8-character display
Output current	I_{nom} has 3 plug-selectable ranges: 800mA, 1600mA, 3000mA	Digital Inputs	16 digital Inputs, 24V approx. 8mA
Dither	Adjustable frequency & amplitude Frequency: 50...400Hz Amplitude: 0...10% of nominal current	Digital Outputs	10 digital Outputs, 24V approx. 100mA
Plug connections	48 pin multipoint connector, according to DIN41612 F48 64 pin multipoint connector, according to DIN41612 C64	Analog Inputs	1 setpoint input 1 limit value input 5 sensor inputs All inputs can be adapted by modules, 12 bit converter resolution
Dimensions	(W/H/D) 50,8mm / 128,4mm / 189,5mm	Analog Outputs	4 analog outputs, ($\pm 10V$, $\pm 20mA$, $\pm 10mA$), 12 bit converter resolution
Protective / filter circuitry	To IEC801, module complies with EMC-regulations	Digital displacement sensor	Ultrasonic displacement sensor (MTS) Incremental displacement sensor SSI sensor
		Interfaces	RS232 (9600 Baud), RS485